

FD-1155
INDUSTRIAL GRADE
CPU BOARD
User' s Guide

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1. OVERVIEW

This is a FD-1155 Pentium Grade CPU Board with VGA, Ethernet, SSD, LCD, Audio.

This chapter provides an overview of your system features and capabilities. The following topics are covered:

- Specification
- Packing List
- Features

1.1 SPECIFICATION

- CPU: Cyrix GX1 BGA 300MHz.
- Chipset: Cyrix CS5530A.
- RAM Memory: Support 1xSODIMM socket ,28MB maximum.
- SSD: Compact Flash Interface X 1.
- Watchdog: Sofeware programmable 1~63sec.
- VGA Display: GX1 UMA.
 - CRT-with HDB 15-pin connector.
 - LCD with 2.0 mm 44-pin Header.
 - LVDS Interface with 2mm 26-pin Header.
- Ethernet: RTL8139C chipset, supports **10/100M baseT** with RJ-45 connector built-in LED.
- Audio: CS5530A on-chip AC97 compatible audio with 2mm 26-pin Box Header on board.
- Super I/O: Winbond 83977TF
 - 1 EIDE** (Ultra DMA33)– with one 2.00 mm 44-pin connector
 - 1 FDC** – with 2.54 mm 34-pin connector.
 - 1 Parallel** – with 2.54 mm 26-pin connector (supports SPP/EPP/ECP mode).
 - 1 RS-232C** – with DB-9 connector located at the bracket.
 - 1 RS-232C/RS485 /IrDA/Touch Screen** – with 2.54 mm 10-pin connector
 - RS-232C is selectable by jumper and use the same connector.
 - IrDA with 2.54mm 5-pin header.
 - Touch Screen uses 2.0mm 3-pin JST connector.
- BIOS: Flash BIOS Award.
- Keyboard/Mouse: PS/2 compatible 6-pin mini-DIN connector located at bracket.
- USB: Built-in **2 ports USB** interface with 2.54mm 10-pin headers.
- RTC: Chipset included, Supports **ACPI function** with 10 years data retention.
- Speaker: Supports on-board buzzer.
- LED Indicators: Power LED, LAN LED at LAN Port.
- Expansion Bus: PC/104.
- Power Connector: One 8-pin 2.5mm JST, 4-pin 5.08mm wafer connector.
- Power Req.: +5V-3.0A maximum and 12V –0.5A maximum.
- CE Design-in: Add EMI components to COM ports, Parallel port, CRT, USB, Keyboard, and PS/2 mouse.
- PC Board: 8 layers, EMI considered. Especially in switching power layout.
- Dimensions: 145 mm x 102 mm (5.7" x 4").

1.2 PACKING LIST

Some accessories are included with the system. Before you begin installing your FD-1155 board, take a moment to make sure that the following items have been included inside the FD-1155 package.

- The quick setup manual
- 1 FD-1155 all-in-one single CPU board
- 1 Hard disk drive interface cable
- 1 Floppy interface cable
- 1 Audio Adapter cable
- 1 LPT cable
- Audio card
- Software Utility CD

1.3 FEATURES

The system provides a number of special features that enhance its reliability, ensure its long-term availability, and improve its expansion capabilities, as well as its hardware structure.

- CPU NS GEODE GX1
- Cyrix CS5530A Chipset
- 1xSODIMM
- Supports DOC Flash Disk
- Audio (AC97)
- 10/100M-Base Ethernet
- Compact Flash (optional)
- AWARD Flash BIOS
- Power Req.: +5V-3.0A maximum and 12V -0.5A maximum.
- Dimensions: 145 mm x 102 mm (5.7"x4").

2. SYSTEM CONTROLLER

This chapter describes the main structure of the FD-1155 CPU board. The following topics are covered:

- Microprocessors
- DMA Controller
- Keyboard Controller
- Interrupt Controller
- Serial Port
- Parallel Port

2.1 MICROPROCESSOR

The FD-1155 uses the NS GEODE GX1 CPU, it is an advanced 32-bit x86 compatible processor offering high performance, fully accelerated 2D graphics, a 64-synchronous DRAM controller and a PCI bus controller, all on a single chip. This latest generation of the MediaGX processor enables a new class of premium performance notebook/desktop, and IPC computer designs.

The MediaGX MMX enhanced processor companion chips provide advanced video and audio functions and permit direct interface to memory. This high-performance 64-bit processor is x86 instruction set compatible and supports MMX technology.

This processor is the latest member of the NS MediaGX family, offering high performance, fully accelerated 2D graphics, synchronous memory interface and a PCI bus controller, all on a single chip. As described in separate manuals, the CS5520 and the CS5530 I/O Companion chips fully enable the features of the MediaGX processor with MMX support. These features include full VGA and VESA video, 16-bit stereo sound, IDE interface, ISA interface, SMM power management, and AT compatibility logic. In addition, the newer CS5530 provides an Ultra DMA/33 interface, MPEG2 assist, and is AC97 Version 2.0 audio compliant.

In addition to the advanced CPU features, the MediaGX processor integrates a host of functions, which are typically implemented with external components. A full-function graphics accelerator provides pixel processing and rendering functions.

The NS MediaGX MMX-Enhanced Processor represents a new generation of x86-compatible 64-bit microprocessors with sixth-generation features. The decoupled load/store unit (within the memory management unit) allows multiple instructions in a single clock cycle. Other features include single-cycle execution, single-cycle instruction decode, 16KB write-back cache, and clock rates up to 266MHz. These features are possible by the use of advanced-process technologies and superpipelining.

2.2 DMA CONTROLLER

The equivalent of two 8237A DMA controllers are implemented on the FD-1155 board. Each controller is a four-channel DMA device that will generate the memory addresses and control signals necessary to transfer information directly between a peripheral device and memory. This allows high-speed information transfer with less CPU intervention. The two DMA controllers are internally cascaded to provide four DMA channels for transfers to 8-bit peripherals (DMA1) and three channels for transfers to 16-bit peripherals (DMA2). DMA2 channel 0 provides the cascade interconnection between the two DMA devices, thereby maintaining IBM PC/AT compatibility.

The Following is the system information for the DMA channels:

Slave with four 8-bit chnls	Master with three 16-bit chnls
DMA Controller 1	DMA Controller 2
Channel 0: Spare	Channel 4(0): Cascade for controller 1
Channel 1: IBM SDLC	Channel 5(1): Spare
Channel 2: Diskette adapter	Channel 6(2): Spare
Channel 3: Spare	Channel 7(3): Spare

DMA Channel Controller

2.3 KEYBOARD CONTROLLER

The 8042 processor is programmed to support the keyboard serial interface. The keyboard controller receives serial data from the keyboard, checks its parity, translates scan codes, and presents it to the system as a byte data in its output buffer. The controller can interrupt the system when data is placed in its output buffer, or wait for the system to poll its status register to determine when data is available.

Data can be written to the keyboard by writing data to the output buffer of the keyboard controller.

Each byte of data is sent to the keyboard controller in a series with an odd parity bit automatically inserted. The keyboard controller is required to acknowledge all data transmissions. Therefore, another byte of data will not be sent to keyboard controller until acknowledgment is received for the previous byte sent. The "output buffer full" interruption may be used for both send and receive routines.

2.4 INTERRUPT CONTROLLER

The equivalent of two 8259 Programmable Interrupt Controllers (PIC) are included on the FD-1155 board. They accept requests from peripherals, resolve priorities on pending interrupts in service, issue interrupt requests to the CPU, and provide vectors which are used as acceptance indices by the CPU to determine which interrupt service routine to execute. These two controllers are cascaded with the second controller representing IRQ8 to IRQ15, which is rerouted through IRQ2 on the first controller.

The following is the system information of interrupt levels:

Interrupt Level	Description
NMI	Parity check
CTRL1	
IRQ0	
IRQ1	
IRQ2	
	CTRL2
	↓
	System timer interrupt from timer 8254
	keyboard output buffer full
	Rerouting to IRQ8 to IRQ15
	IRQ8:Real time clock
	IRQ9:Reserved
	IRQ10:LAN adapters(based on PCI INT routing)
	IRQ12:Reserved for PS/2 mouse
	IRQ13:Math.Co-processor
	IRQ14:Hard disk adapter
	IRQ15:Hard disk adapter
IRQ3	Serial port(depends on setup assignment)
IRQ4	Serial port(depends on setup assignment)
IRQ5	Reserved
IRQ6	Reserved for floppy disk adapter
IRQ7	Parallel port 1

Interrupt Controller

2.4.1 I/O Port Address Map

Hex Range	Device
000-01F	DMA controller 1
020-021	Interrupt controller 1
022-023	Cyrix CS5530
040-04F	Timer 1
050-05F	Timer 2
060-06F	8042 keyboard/controller
070-071	Real-time clock (RTC), non-maskable interrupt (NMI)
080-09F	DMA page registers
0A0-0A1	Interrupt controller 2
0C0-0DF	DMA controller 2
0F0	Clear Math Co-processor
0F1	Reset Math Co-processor
0F8-0FF	Math Co-processor
170-178	Reserved for Fixed disk 1
1F0-1F8	Fixed disk 0
201	Reserved for Game port
208-20A	EMS register 0
210-213	SSD
214	WatchDog
218-21A	EMS register 1
278-27F	Parallel printer port (depends on setup assignment)
290-293	SSD
2E8-2EF	Serial port (depends on setup assignment)
2F8-2FF	Serial port (depends on setup assignment)
300-31F	Prototype card/streaming type adapter
320-33F	Reserved
378-37F	Parallel printer port (depends on setup assignment)
380-38F	SDLC, bisynchronous
3A0-3AF	Bisynchronous
3B0-3BF	Monochrome display and printer port 3 (LPT 3)
3C0-3CF	EGA/VGA adapter
3D0-3DF	Color/graphics monitor adapter
3E8-3EF	Serial port 3 (depends on setup assignment)
3F0-3F7	Reserved for diskette controller
3F8-3FF	Serial port (depends on setup assignment)

I/O Port Address Map

2.4.2 Real-Time Clock and Non-Volatile RAM

The FD-1155 contains a real-time clock compartment that maintains the date and time in addition to storing configuration information about the computer system. It contains 14 bytes of clock and control registers and 114 bytes of general purpose RAM. Because of the use of CMOS technology, it consumes very little power and can be maintained for long periods of time using an internal Lithium battery. The contents of each byte in the CMOS RAM are listed as follows:

Address	Description
00	Seconds
01	Second alarm
02	Minutes
03	Minute alarm
04	Hours
05	Hour alarm
06	Day of week
07	Date of month
08	Month
09	Year
0A	Status register A
0B	Status register B
0C	Status register C
0D	Status register D
0E	Diagnostic status byte
0F	Shutdown status byte
10	Diskette drive type byte, drive A and B
11	Fixed disk type byte, drive C
12	Fixed disk type byte, drive D
13	Reserved
14	Equipment byte
15	Low base memory byte
16	High base memory byte
17	Low expansion memory byte
18	High expansion memory byte
19-2D	Reserved
2E-2F	2-byte CMOS checksum
30	Low actual expansion memory byte
31	High actual expansion memory byte
32	Date century byte
33	Information flags (set during power on)
34-7F	Reserved for system BIOS

Real-Time Clock & Non-Volatile RAM

2.4.3 Timer

The FD-1155 provides three programmable timers, each with a timing frequency of 1.19 MHz.

Timer 0 The output of this timer is tied to interrupt request 0. (IRQ 0)

Timer 1 This timer is used to trigger memory refresh cycles.

Timer 2 This timer provides the speaker tone.
Application programs can load different counts into this timer to generate various sound frequencies.

2.5 SERIAL PORT

The ACEs (Asynchronous Communication Elements ACE1 to ACE4) are not only used to convert parallel data to a serial format on the transmit side but also used to convert serial data to parallel on the receiver side. The serial format, in order of transmission and reception, is a start bit, followed by five to eight data bits, a parity bit (if programmed) and one, 1.5 (in a five-bit format only) or two stop bits (in a 6,7, or 8-bit format). The ACEs are capable of handling divisors of 1 to 65535, and produce a 16x clock for driving the internal transmitter logic.

The provision is not only included the use of this 16x clock to drive the receiver logic. But also included in the ACE as a completed MODEM control capability, and a processor interrupt system that may be software tailored to the computing time required to handle the communications link.

The following table is a summary of each ACE accessible register

DLAB	Port Address	Register
0	base + 0	Receiver buffer (read)
		Transmitter holding register (write)
0	base + 1	Interrupt enable
X	base + 2	Interrupt identification (read only)
X	base + 3	Line control
X	base + 4	MODEM control
X	base + 5	Line status
X	base + 6	MODEM status
X	base + 7	Scratched register
1	base + 0	Divisor latch (least significant byte)
1	base + 1	Divisor latch (most significant byte)

ACE Accessible Registers

(1) Receiver Buffer Register (RBR)

Bit 0-7: Received data byte (Read Only)

(2) Transmitter Holding Register (THR)

Bit 0-7: Transmitter holding data byte (Write Only)

(3) Interrupt Enable Register (IER)

Bit 0: Enable Received Data Available Interrupt (ERBFI)
 Bit 1: Enable Transmitter Holding Empty Interrupt (ETBEI)
 Bit 2: Enable Receiver Line Status Interrupt (ELSI)
 Bit 3: Enable MODEM Status Interrupt (EDSSI)
 Bit 4: Must be 0
 Bit 5: Must be 0
 Bit 6: Must be 0
 Bit 7: Must be 0

(4) Interrupt Identification Register (IIR)

Bit 0: "0" if Interrupt Pending
 Bit 1: Interrupt ID Bit 0
 Bit 2: Interrupt ID Bit 1
 Bit 3: Must be 0
 Bit 4: Must be 0
 Bit 5: Must be 0
 Bit 6: Must be 0
 Bit 7: Must be 0

(5) Line Control Register (LCR)

Bit 0: Word Length Select Bit 0 (WLS0)

Bit 1: Word Length Select Bit 1 (WLS1)

WLS1	WLS0	Word Length
0	0	5 Bits
0	1	6 Bits
1	0	7 Bits
1	1	8 Bits

Bit 2: Number of Stop Bit (STB)

Bit 3: Parity Enable (PEN)

Bit 4: Even Parity Select (EPS)

Bit 5: Stick Parity

Bit 6: Set Break

Bit 7: Divisor Latch Access Bit (DLAB)

(6) MODEM Control Register (MCR)

Bit 0: Data Terminal Ready (DTR)

Bit 1: Request to Send (RTS)

Bit 2: Out 1 (OUT 1)

Bit 3: Out 2 (OUT 2)

Bit 4: Loop

Bit 5: Must be 0

Bit 6: Must be 0

Bit 7: Must be 0

(7) Line Status Register (LSR)

Bit 0: Data Ready (DR)

Bit 1: Overrun Error (OR)

Bit 2: Parity Error (PE)

Bit 3: Framing Error (FE)

Bit 4: Break Interrupt (BI)

Bit 5: Transmitter Holding Register Empty (THRE)

Bit 6: Transmitter Shift Register Empty (TSRE)

Bit 7: Must be 0

(8) MODEM Status Register (MSR)

Bit 0: Delta Clear to Send (DCTS)

Bit 1: Delta Data Set Ready (DDSR)

Bit 2: Training Edge Ring Indicator (TERI)

Bit 3: Delta Receive Line Signal Detect (DSLSD)

Bit 4: Clear to Send (CTS)

Bit 5: Data Set Ready (DSR)

Bit 6: Ring Indicator (RI)

Bit 7: Received Line Signal Detect (RSLD)

(9) Divisor Latch (LS, MS)

	LS	MS
Bit 0:	Bit 0	Bit 8
Bit 1:	Bit 1	Bit 9
Bit 2:	Bit 2	Bit 10
Bit 3:	Bit 3	Bit 11
Bit 4:	Bit 4	Bit 12
Bit 5:	Bit 5	Bit 13
Bit 6:	Bit 6	Bit 14
Bit 7:	Bit 7	Bit 15

Desired Baud Rate	Divisor Used to Generate 16x Clock
300	384
600	192
1200	96
1800	64
2400	48
3600	32
4800	24
9600	12
14400	8
19200	6
28800	4
38400	3
57600	2
115200	1

Serial Port Divisor Latch

2.6 PARALLEL PORT

(1) Register Address

Port Address	Read/Write	Register
base + 0	Write	Output data
base + 0	Read	Input data
base + 1	Read	Printer status buffer
base + 2	Write	Printer control latch

Registers' Address

(2) Printer Interface Logic

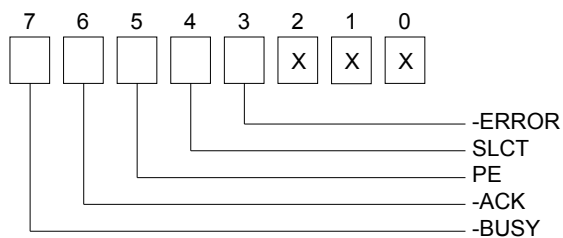
The parallel port of the W83977F-A is for attaching various devices that accept eight bits of parallel data at standard TTL level.

(3) Data Swapper

The system microprocessor can read the contents of the printer's Data Latch through the Data Swapper by reading the Data Swapper address.

(4) Printer Status Buffer

The system microprocessor can read the printer status by reading the address of the Printer Status Buffer. The bit definitions are described as follows:



Printer Status Buffer

NOTE: X presents not used.

Bit 7: This signal may become active during data entry, when the printer is off-line during printing, or when the print head is changing position or in an error state. When Bit 7 is active, the printer is busy and cannot accept data.

Bit 6: This bit represents the current state of the printer's ACK signal. A0 means the printer has received the character and is ready to accept another. Normally, this signal will be active for approximately 5 microseconds before receiving a BUSY message stops.

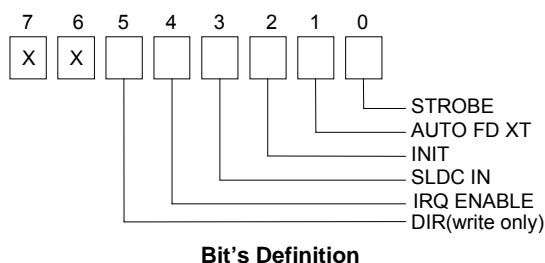
Bit 5: A1 means the printer has detected the end of the paper.

Bit 4: A1 means the printer is selected.

Bit 3: A0 means the printer has encountered an error condition.

(5) Printer Control Latch & Printer Control Swapper

The system microprocessor can read the contents of the printer control latch by reading the address of printer control swapper. Bit definitions are as follows:



NOTE: X presents not used.

Direction control bit. When logic 1, the output buffers in the parallel port are disabled allowing data driven from external sources to be read; when logic 0, they work as a printer port. This bit is writing only.

Bit 5: A1 in this position allows an interrupt to occur when ACK changes from low state to high state.

Bit 4: A1 in this bit position selects the printer.

Bit 3: A0 starts the printer (50 microseconds pulse, minimum).

Bit 2: A1 causes the printer to line-feed after a line is printed.

Bit 1: A0.5 microsecond minimum highly active pulse clocks data into the printer. Valid data must be present for a minimum of 0.5 microseconds before and after the strobe pulse.

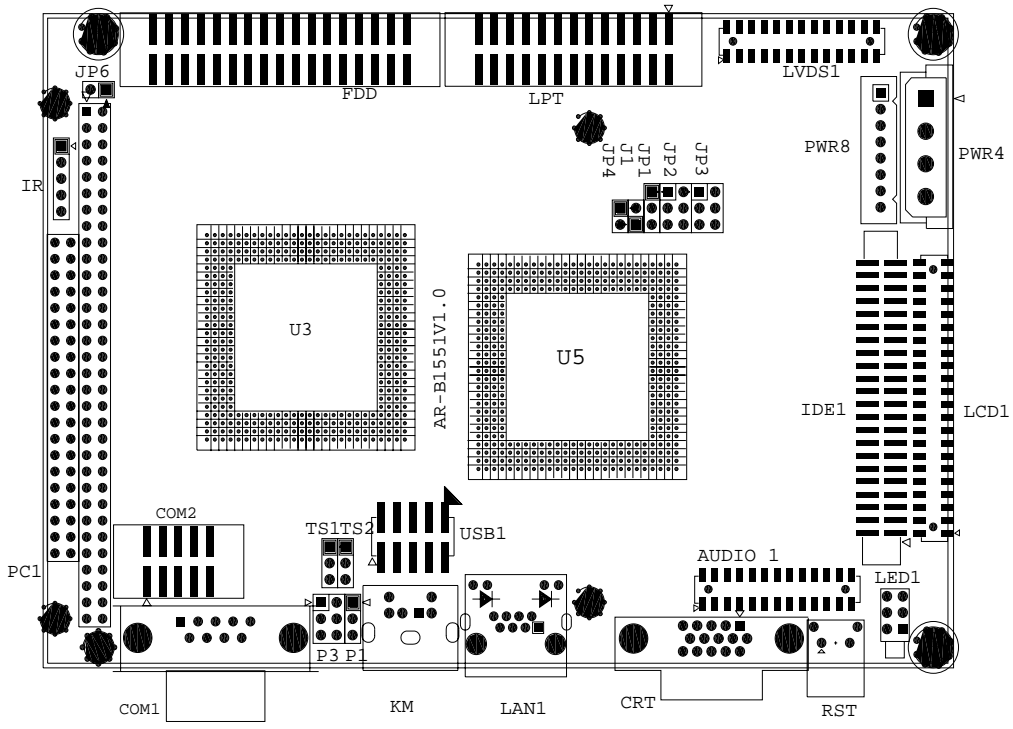
3. SETTING UP THE SYSTEM

This section describes pin assignments for the system's external connectors and the jumper settings.

- Overview
- System Setting

3.1 OVERVIEW

FD-1155 is a Pentium Grade CPU Board with Ethernet, DOC, SSD, and Compact Flash (optional) functions. This section provides the hardware's jumper settings, the connectors' locations, and the pin assignments. The #1 pin assignments have all been designed on the right side of the board with a "block" indication on the diagram.



External System Location

3.2 SYSTEM SETTING

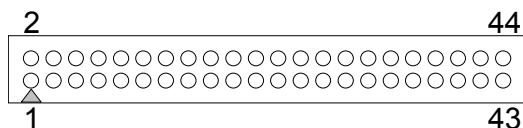
Jumper pins allow you to set specific system parameters. Set them by changing the pin location of jumper blocks. (A jumper block is a small plastic-encased conductor that slips over the pins.) To change a jumper setting, remove the jumper from its current location with your fingers or small needle-nosed pliers. Place the jumper over the two pins designated for the desired setting. Press the jumper evenly onto the pins. Be careful not to bend the pins.

CAUTION: Do not touch any electronic components unless you are safely grounded. Wear a grounded wrist strap or touch an exposed metal part of the system unit chassis. The static discharges from your fingers can permanently damage electronic components.

3.2.1 Hard Disk (IDE) Connector

44-Pin Hard Disk (IDE) Connector (IDE1)

FD-1155 also provides IDE interface 44-pin connector to connect with the hard disk device.



Pin	Signal	Pin	Signal
1	-RESET	2	GROUND
3	DATA 7	4	DATA 8
5	DATA 6	6	DATA 9
7	DATA 5	8	DATA 10
9	DATA 4	10	DATA 11
11	DATA 3	12	DATA 12
13	DATA 2	14	DATA 13
15	DATA 1	16	DATA 14
17	DATA 0	18	DATA 15
19	GROUND	20	NOT USED
21	IDEDREQ	22	GROUND
23	-IOW A	24	GROUND
25	-IOR A	26	GROUND
27	IDEIORDYA	28	GROUND
29	-DACKA	30	GROUND
31	AINT	32	GROUND
33	SA 1	34	Not Used
35	SA 0	36	SA 2
37	CS 0	38	CS 1
39	HD LED A	40	GROUND
41	VCC	42	VCC
43	GROUND	44	Not Used

Hard Disk (IDE1) Connector

3.2.2 FDD Port Connector (FDD)

The FD-1155 provides a 34-pin header type connector for supporting up to two floppy disk drives. To enable or disable the floppy disk controller, please use the BIOS Setup program.

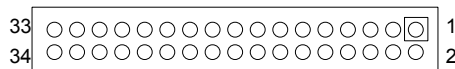


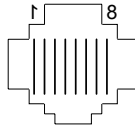
Figure 0-1 CN3: FDD Port connector

Pin	Signal	Pin	Signal
1-33(odd)	GROUND	18	DIRECTION
2	DRVEN 0	20	-STEP OUTPUT PULSE
4	NOT USED	22	-WRITE DATA
6	DRVEN 1	24	-WRITE GATE
8	-INDEX	26	-TRACK 0
10	-MOTOR ENABLE 0	28	-WRITE PROTECT
12	-DRIVE SELECT 1	30	-READ DATA
14	-DRIVE SELECT 0	32	-SIDE 1 SELECT
16	-MOTOR ENABLE 1	34	DISK CHANGE

Table 0-1 FDD Pin Assignment

3.2.3 Network Setting (LAN1)

The LAN1 RJ-45&LED headers are the standard network headers. The following table is the pin assignment.

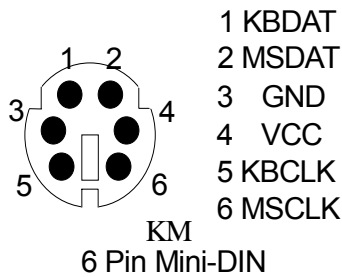


PIN (CN12)	FUNCTION
1	TPTX+
2	TPTX -
3	TPRX+
4	Not Used
5	Not Used
6	TPRX -
7	Not Used
8	Not Used

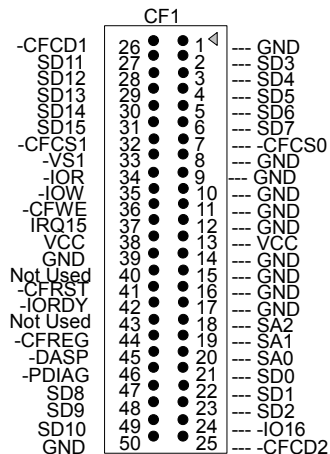
RJ-45 Pin Assignment

3.2.4 PS/2 KB/Mouse Connector (KM)

To use the PS/2 interface, the connector for the PS/2 KB/mouse is a Mini-DIN 6-pin connector. This adapter cable is mounted on a bracket and is included in your FD-1155 package. Pin assignments for the PS/2 port connector are as follows:

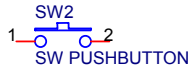


3.2.5 Compact Flash Connector (CF1)



3.2.6 Reset Header (RST)

The RST is a reset switch. Shorting these two pins will reset the system.



3.2.7 Power Connector (PWR4, PWR8)

(1) 8-Pin Power Connector (PWR8)

PWR8 is an 8-pin power connector. You can directly connect the power supply to the onboard power connector for stand-alone applications.

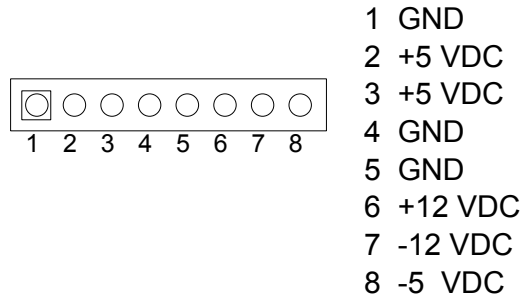


Figure 0-2 PWR8: 8-Pin Power Connector

(2) 4-Pin Power Connector (PWR4)

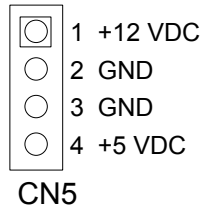
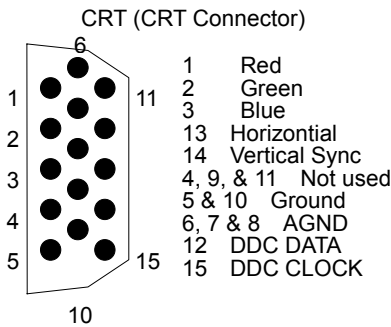


Figure 0-3 PWR4: 4-Pin Power Connector

3.2.8 CRT Connector (CRT)



3.2.9 LCD Supported Voltage Select (JP2)

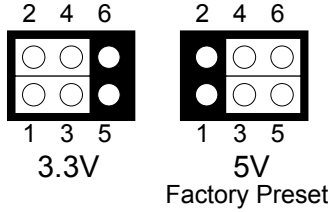


Figure 0-4 JP2: LCD Supported Voltage Select

3.2.10 LCD Panel Display Connector (LCD1)

Attach a display panel connector to this 44-pin connector with pin assignments as shown below:

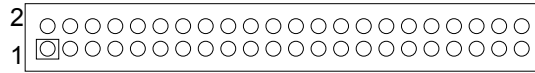
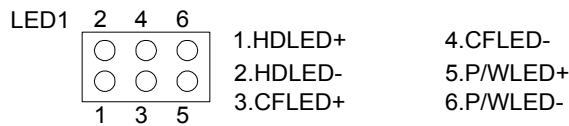


Figure 0-5 LCD1: LCD Display Connector

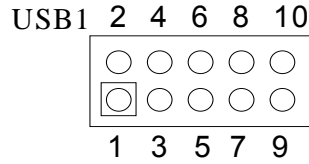
Pin	Signal	Pin	Signal
1	GND	2	SHFCLK
3	GND	4	LP
5	FLM	6	GND
7	NC	8	NC
9	P0 (B0)(LSB)	10	P1 (B1)
11	P2 (B2)	12	P3 (B3)
13	GND	14	P4 (B4)
15	P5 (B5)(MSB)	16	NC
17	NC	18	P6 (G0)(LSB)
19	P7 (G1)	20	GND
21	P8 (G2)	22	P9 (G3)
23	P10 (G4)	24	P11 (G5)(MSB)
25	NC	26	NC
27	GND	28	P12 (R0)(LSB)
29	P13 (R1)	30	P14 (R2)
31	P15 (R3)	32	P16 (R4)
33	P17 (R5)(MSB)	34	GND
35	VCC	36	VCC
37	+12V	38	+12V
39	GND	40	GND
41	DE	42	ENABLK
43	GND	44	VEE

Table 0-2 LCD Display Pin Assignment

3.2.11 LED Header (LED1)



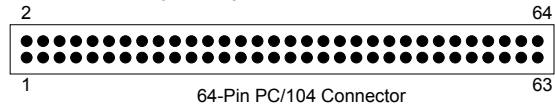
3.2.12 USB Connector(USB1)



Pin	Description	Pin	Description
1	USB1V	2	USB2V
3	USBD1F-	4	USBD2F-
5	USBD1F+	6	USBD2F+
7	GND	8	GND
9	CASE	10	CASE

3.2.13 PC104 Connector

(1) 64-Pin PC/104 Connector Bus A & B (PC1A)



PC1A

		1 2			
-IOCHCK	A1 ●	●	B1	---	GND
SD7	A2 ●	●	B2	---	RSTDRV
SD6	A3 ●	●	B3	---	+5 VDC
SD5	A4 ●	●	B4	---	IRQ9
SD4	A5 ●	●	B5	---	-5 VDC
SD3	A6 ●	●	B6	---	DRQ2
SD2	A7 ●	●	B7	---	-12 VDC
SD1	A8 ●	●	B8	---	-ZWS
SD0	A9 ●	●	B9	---	+12
IOCHRDY	A10 ●	●	B10	---	KEY
AEN	A11 ●	●	B11	---	-SMEMW
SA19	A12 ●	●	B12	---	-SMEMR
SA18	A13 ●	●	B13	---	-IOW
SA17	A14 ●	●	B14	---	-IOR
SA16	A15 ●	●	B15	---	-DACK3
SA15	A16 ●	●	B16	---	DRQ3
SA14	A17 ●	●	B17	---	-DACK1
SA13	A18 ●	●	B18	---	DRQ1
SA12	A19 ●	●	B19	---	-REFRESH
SA11	A20 ●	●	B20	---	BUSCLK
SA10	A21 ●	●	B21	---	IRQ7
SA9	A22 ●	●	B22	---	IRQ6
SA8	A23 ●	●	B23	---	IRQ5
SA7	A24 ●	●	B24	---	IRQ4
SA6	A25 ●	●	B25	---	IRQ3
SA5	A26 ●	●	B26	---	-DACK2
SA4	A27 ●	●	B27	---	TC
SA3	A28 ●	●	B28	---	BALE
SA2	A29 ●	●	B29	---	+5
SA1	A30 ●	●	B30	---	OSC
SA0	A31 ●	●	B31	---	GND
GND	A32 ●	●	B32	---	GND

Figure PC1A: 64-Pin PC/104 Connector Bus A & B

(2) 40-Pin PC/104 Connector Bus C & D (PC1B)

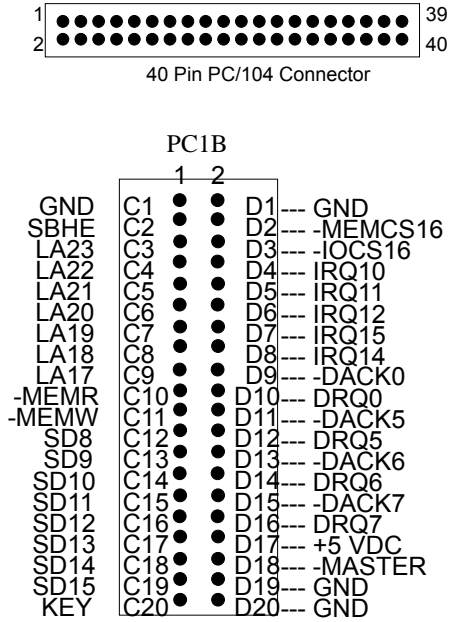
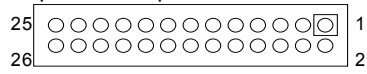


Figure PC1B: 40-Pin PC/104 Connector Bus C & D

3.2.14 Parallel Port Connector (LPT)

The connector for the parallel port is a 26 pins female connector.



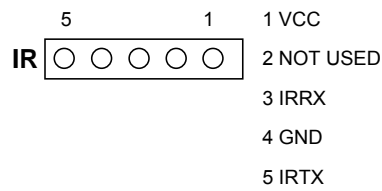
Parallel Port Connector

CN8	DB-25	Signal	CN8	DB-25	Signal
1	1	-Strobe	2	14	-Auto Form Feed
3	2	Data 0	4	15	-Error
5	3	Data 1	6	16	-Initialize
7	4	Data 2	8	17	-Printer Select In
9	5	Data 3	10	18	Ground
11	6	Data 4	12	19	Ground
13	7	Data 5	14	20	Ground
15	8	Data 6	16	21	Ground
17	9	Data 7	18	22	Ground
19	10	-Acknowledge	20	23	Ground
21	11	Busy	22	24	Ground
23	12	Paper	24	25	Ground
25	13	Printer Select	26	--	Not Used

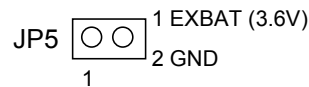
Parallel Port Pin Assignments

3.2.15 IR. Header (IR)

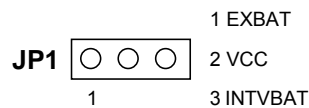
The Infra-red Header pins assignments are as follow:



3.2.16 Ext. Battery (JP5)



3.2.17 Battery Jumper (JP1)



1-2	2-3
External Battery	On-Board Battery

JP1: Battery Setting

3.2.18 COM1, COM2 (COM1, COM2)

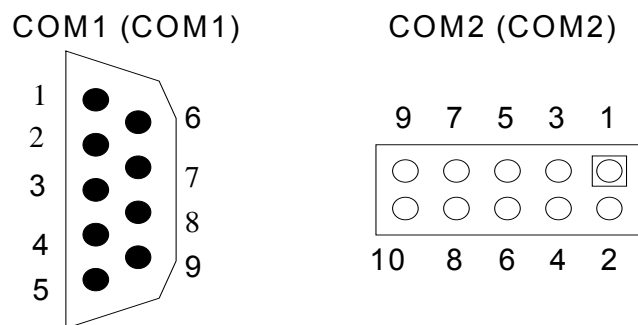


Figure 0-6 COM1 & COM2: RS-232 Connector

CN5	CN6	Signal	CN5	DB6	Signal
1	1	/DCD	6	6	/CTS
2	2	/DSR	7	7	/DTR
3	3	RXD	8	8	/RI
4	4	/RTS	9	9	GND
5	5	TXD	10	--	GND

Table 0-3 RS-232 Connector Pin Assignment

(1) RS-232/RS-485 Select for COM2 (P1 & P3)

The P1&P3 jumper is used to choose between the use of the on-board RS-232 or RS-485 for the COM2.

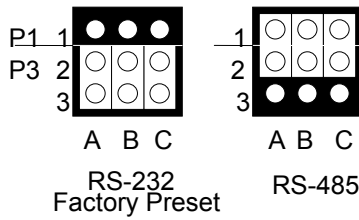


Figure 3-10 P1 & P3: RS-232/RS-485 Select for COM2

(2) RS-485 Terminator Select (JP6)

When there is only one line the setting should be left off, but if you are using multiple blocks on a single line this should be set to “ON” in order to properly terminate the connection for better transmission of data

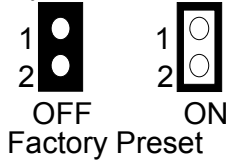


Figure 0-7 JP6: RS-485 Terminator Select

3.2.19 Touch Screen Connector (T.S.1 & T.S.2)

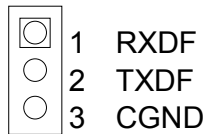


Figure 0-8 T.S.1&T.S.2: Touch Screen Connector

3.2.20 D.O.C. Memory Address Select (JP4)

This section provides the information about how to use the D.O.C. (DiskOnChip). There divided two parts: hardware setting and software configuration.

- Step 1:** Use JP4 to select the correct D.O.C. memory address.
- Step 2:** Insert programmed DiskOnChip into sockets U22 setting as DOC.
- Step 3:** Line up and insert the FD-1155 card into slot of your computer.

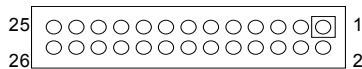


Figure 0-9 JP4: D.O.C. Memory Address Select

JP4	Address	Note
OFF	C8000	Factory Preset
ON	D0000	

Table 0-4 D.O.C. Memory Address

3.2.21 26-Pin Audio Connector (AUDIO1)

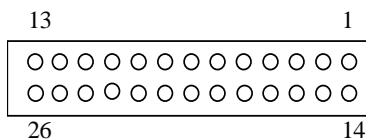


Audio Connector

CN9	Signal	CN9	Signal
1	CDINL	2	LININL
3	CDINR	4	LININR
5	VCC	6	NC
7	LINOUTL	8	MICIN
9	LINOUTR	10	PCBEEP
11	GNDAUD	12	GND
13	NC	14	NC
15	GNDAUD	16	GND
17	NC	18	NC
19	NC	20	NC
21	NC	22	NC
23	NC	24	NC
25	GNDAUD	26	GND

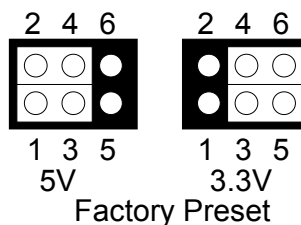
Table 0-5 Audio Connector Pin Assignment

3.2.22 LVDS Connector (LVDS1)



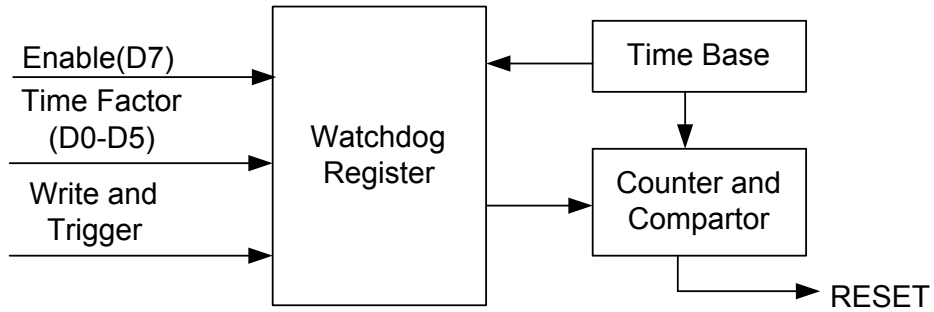
LVDS1	Signal	LVDS1	Signal
1	TXOUT0-	14	GND
2	TXOUT0+	15	GND
3	TXOUT1-	16	VTX5
4	TXOUT1+	17	VTX5
5	TXOUT2-	18	NC
6	TXOUT2+	19	GND
7	TXCLK-	20	GND
8	TXCLK+	21	VTX12
9	TXOUT3-	22	VTX12
10	TXOUT3+	23	GND
11	VTKBP	24	NC
12	VTX5	25	NC
13	VTX5	26	NC

3.2.23 LVDS Supported Voltage Select (JP3)



3.3 WATCHDOG TIMER

This section describes how to use the Watchdog Timer disabled, enabled, and trigger. The AR-B1570 is equipped with a programmable time-out period watchdog timer that occupies I/O post 214H. User can use the program to enable the watchdog timer. Once you enable the watchdog timer, the program should trigger it every time before it times out. And because of the system hang up, your program fails to trigger and disable the timer before it times out. It will generate a reset signal to reset the system. The time-out period can be programmed to be 0 to 63 seconds.



Watchdog Block Diagram

3.3.1 Watchdog Timer Setting

The watchdog timer is a circuit that maybe be used from your program software to detect crash or hang up. The Watchdog timer is automatically disabled after reset. Once you enabled the watchdog timer, your program should trigger the watchdog timer every time before it times out. After you trigger the watchdog timer, it will be set to zero and start to count again. If your program fails to trigger the watchdog timer before time out, it will generate a reset pulse to reset the system or trigger the IRQ 9 signal in order to tell your system that the watchdog time is out.

Please refer to the following table in order to properly program Watchdog function

	D7	D6	D5 D4 D3 D2 D1 D0
1	Enable	Reset	Time period
0	Disable	IRQ 9	

Users could test watchdog function under 'Debug' program as follow:

```
C:>debug
● O 214 C8H
  Generally, watchdog function would
  reset system after 8 seconds
● O 214 0H
  Disable watchdog function
```

```
C:>debug
● O 214 88H
  Generally, watchdog function would
  generate IRQ 9 after 8 seconds
● O 214 0H
  Disable watchdog function
```

3.3.2 Watchdog Timer Trigger

After you enable the watchdog timer, your program must write the same factor as enabling to the watchdog register at least once every time-out period to its previous setting. You can change the time-out period by writing another timer factor to the watchdog register at any time, and you must trigger the watchdog before the new time-out period in next trigger.

4. INSTALLATION

This chapter describes the installation procedure. The following topics are covered:

- Overview
- Utility Diskettes

4.1 OVERVIEW

This chapter provides information for you to set up a working system based on the FD-1155 CPU board. Please carefully read the details of the CPU board's hardware descriptions before installation. Pay special attention to the jumper settings, switch settings and cable connections.

Follow steps listed below for proper installation:

- Step 1:** Read the CPU board's hardware description in this manual.
- Step 2:** Set jumpers.
- Step 3:** Make sure that the power supply connected to your FD-1155 CPU board is turned off.
- Step 4:** Connect all necessary cables. Make sure that the HDC; serial and parallel cables are connected to pin 1 of the related connector (not upside down).
- Step 5:** Connect the hard disk flat cables from the CPU board to the drives. Connect a power source to drive.
- Step 6:** Plug the keyboard into the keyboard connector.
- Step 7:** Turn on the power.
- Step 8:** Configure your system with the BIOS Setup program (section 5) then re-boot your system.
- Step 9:** If the CPU board does not work, turn off the power and read the hardware description carefully again.
- Step 10:** If the CPU board still does not perform properly, return the board to your dealer for immediate service.

4.2 UTILITY DISKETTE

The FD-1155 provides CD.

4.2.1 Driver Installation

The FD-1155 provides LAN function drivers for the WIN95, WIN98, WIN2000, WINCE, LINUX, and NT. The driver can auto-setup in the specified mode. The user must first decompress the compressed file.

The 1st step: Decompress the zip files included in the CD to your hard disk.

The 2nd step: Execute the corresponding files to setup the system.

The files list and descriptions are as follow:

Disk 1	
Files	README.TXT 391 09-22-00 11:17 README.TXT GEODEW~1 <DIR> 09-22-00 10:53 Geode win9x WINCED~1 <DIR> 09-22-00 10:53 WinCE driver
Descriptions	1. GEODE win9x Includes auto-execution program that will setup/install Geode Media drivers in Windows 9X environment. 2. WinCE driver Includes the GxM drivers needed in Win CE environment.
Disk 2	
Files	NT4~1 0DR <DIR> 09-22-00 10:53 NT4.0 driver LINUXD~1 <DIR> 09-22-00 10:53 Linux driver WIN200~1 <DIR> 09-22-00 10:53 Win2000 driver README.TXT 1,611 04-23-99 11:48 README.TXT
Descriptions	1. NT4.0 driver Includes the GxM drivers needed in NT4.0 environment. 2. Linux driver Includes the GxM drivers needed in Linux environment. 3. Win2000 driver Includes the GxM drivers needed in Win2000 environment.
Disk 3	
Files	8139SW.EXE
Description	An auto extract file that includes: 1. Device drivers of RTL8139A for various operating systems 2. LAN Configuration EEPROM programmer 3. Diagnostic and modification program for RTL8139

5. BIOS CONSOLE

This chapter describes the FD-1155 BIOS menu displays and explains how to perform common tasks needed to get up and running, and presents detailed explanations of the elements found in each of the BIOS menus. The following topics are covered:

- BIOS Setup Overview
- Standard CMOS Setup
- BIOS Features Setup
- Chipset Features Set
- PNP/PCI Configuration
- Load Default Setting
- Integrated Peripherals
- Password Setting
- IDE HDD Auto Detection
- BIOS Exit

5.1 BIOS SETUP OVERVIEW

Once you enter Award BIOS CMOS Setup Utility by holding the "Delete" button during boot-up, the Main Menu will appear on the screen. The Main Menu allows you to select from various setup functions and two exit choices. Use arrow keys to select among the items and press <Enter> to accept or enter the sub-menu.

ROM PCI/ISA BIOS (2A434AVF)
CMOS SETUP UTILITY
AWARD SOFTWARE, INC.

STANDARD CMOS SETUP	INTEGRATED PERIPHERALS
BIOS FEATURES SETUP	SUPERVISOR PASSWORD
CHIPSET FEATURES SETUP	USER PASSWORD
PNP/PCI CONFIGURATION	IDE HDD AUTO DETECTION
LOAD BIOS DEFAULTS	SAVE & EXIT SETUP
LOAD SETUP DEFAULTS	EXIT WITHOUT SAVING
Esc: Quit	↑↓→←: Select Item
F10: Save & Exit Setup	(Shift) F2: Change Color
Time, Date, Hard Disk Type...	

BIOS Setup Main Menu

- CAUTION:**
1. FD-1155 BIOS the factory-default setting is used to the <LOAD BIOS DEFAULTS> Acrosser recommends using the BIOS default setting, unless you are very familiar with the setting function, or you can contact the technical support engineer.
 2. If the BIOS settings are lost, the CMOS will detect the <LOAD SETUP DEFAULTS> to boot the operation system, this option will reduce the performance of the system. Acrosser recommends choosing the <LOAD BIOS DEFAULTS> in the main menu. This option gives best-case values that should optimize system performance.
 3. The BIOS settings are described in detail in this section.

5.2 STANDARD CMOS SETUP

The <Standard CMOS Setup> option allows you to record some basic system hardware configuration and set the system clock and error handling. If the CPU board is already installed in a working system, you will not need to select this option anymore.

```

ROM PCI/ISA BIOS (2A434AVF)
STANDARD CMOS SETUP
AWARD SOFTWARE, INC.

Date (mm:dd:yyyy): Tue, Mar 16, 2000
Time (hh:mm:ss): 16:39:30

      <type>
Drive C : 0 ( 0Mb)  0  0  0  0  0  0  AUTO
Drive D:  0 ( 0Mb)  0  0  0  0  0  0  AUTO

Drive A:  None
Drive B:  None
Video:    EGA/VGA
Halt On:  All, But Keyboard

Base Memory:  640K
Extended Memory: 29184K
Other Memory:  384K

Total Memory:  30208K

Esc: Quit      ↑↓→←:  Select Item  PU/PD/+/-:  Modify
F1:  Help      (Shift) F2:  Change Color

```

Standard CMOS Setup

Date & Time Setup

Highlight the <Date> field and then press the [Page Up] / [Page Down] or [+]/[-] keys to set the current date. Follow the month, day and year format.

Highlight the <Time> field and then press the [Page Up] / [Page Down] or [+]/[-] keys to set the current date. Follow the hour, minute and second format.

The user can bypass the date and time prompts by creating an AUTOEXEC.BAT file. For information on how to create this file, please refer to the MS-DOS manual.

Hard Disk Setup

The BIOS supports various types for user settings, The BIOS supports <Pri Master>, <Pri Slave>, <Sec Master> and <Sec Slave> so the user can install up to two hard disks. For the master and slave jumpers, please refer to the hard disk's installation descriptions and the hard disk jumper settings in section three of this manual.

You can select <AUTO> under the <TYPE> and <MODE> fields. This will enable auto detection of your IDE drives during boot-up. This will allow you to change your hard drives (with the power off) and then power on without having to reconfigure your hard drive type. If you use older hard disk drives, which do not support this feature, then you must configure the hard disk drive in the standard method by choosing the HDD type, which should be noted directly on the HDD.

Floppy Setup

The <Standard CMOS Setup> option records the types of floppy disk drives installed in the system.

To enter the configuration value for a particular drive, highlight its corresponding field and then select the drive type using the left-or right-arrow key.

Video

This option selects the type of adapter used for the primary system monitor that must match your video display card and monitor. Although secondary monitors are supported, you do not have to select the type in Setup.

You have two ways to boot up the system:

1. When VGA as primary and monochrome as secondary, the selection of the video type is "VGA Mode".
2. When monochrome as primary and VGA as secondary, the selection of the video type is "Monochrome Mode".

EGA/VGA	Enhanced Graphics Adapter/Video Graphics Array. For EGA, VGA, SEGA, or VGA monitor adapters
CGA 40	Color Graphics Adapter, power up in 40 column mode
CGA 80	Color Graphics Adapter, power up in 80 column mode
MONO	Monochrome adapter, includes high resolution monochrome adapters

Halt On

This option determines whether the computer will stop if an error is detected during power up.

No errors	The system boot will not be stopped for any error that may be detected.
All errors	Whenever the BIOS detects a non-fatal error the system will be stopped and you will be prompted.
All, But Keyboard	The system boot will not stop for a keyboard error, it will stop for all other errors.
All, But Diskette	The system boot will not stop for a disk error, it will stop for all other errors.
All, But Disk/Key	The system boot will not stop for a keyboard or disk error, it will stop for all other errors.

5.3 BIOS FEATURES SETUP

The <BIOS FEATURES SETUP> option consists of configuration entries that allow you to improve your system performance, or let you set up some system features according to your preference. Some entries here are required by the CPU board's design to remain in their default settings for optimal performance.

It is suggested that you leave the settings on the factory default unless you are well versed in BIOS features.

ROM PCI/ISA BIOS (2A434AVF)
 BIOS FEATURES SETUP
 AWARD SOFTWARE, INC.

CPU Internal Cache : Enabled	Video BIOS Shadow : Enabled
Quick Power On Self Test : Enabled	
Boot Sequence : C, CDROM,A	
	Cyrix 6x86/MII CPUID : Enabled
Boot Up NumLock Status : On	
Boot Up System Speed : High	
Gate A20 Option : Fast	
Memory Parity Check : Disabled	
Typematic Rate Setting : Enabled	
Typematic Rate (Chars/Sec) : 30	
Typematic Delay (Msec) : 250	
Security Option : Setup	Esc: Quit ↑↓→←: Select Item
PCI/VGA Palette Snoop : Disabled	F1: Help PU/PD/+/-: Modify
	F5: Old Values (Shift) F2: Change Color
	F6: Load BIOS Defaults
	F7: Load Setup Defaults

BIOS Features Setup

CPU Internal Cache/External Cache

The two functions speed up memory access. However, it depends on CPU/chipset design. If your CPU is without Internal cache then this item <CPU Internal Cache> will not be show. The FD-1155's GX1 Cyrix CPU has an internal cache and will automatically be set to <enabled>.

Quick Power On Self Test

This option speeds up Power On Self Test (POST) after you power on the computer. If it is set to Enable, BIOS will shorten or skip some items' checks during POST.

Boot Sequence

The option determines which drive computer searches first for the disk operating system.

Boot Up NumLock Status

This item is used to activate the NumLock function upon system boot. If the setting is on, after a boot, the NumLock light is lit, and the user can use the number keys.

Boot Up System Speed

This item is used to choose the boot-up speed of system. The choices provided are <LOW> and <HIGH>.

Gate A20 Option

This item is chosen as <Normal>, the A20 signal is controlled by keyboard controller or chipset hardware. The selection is "Fast" means the A20 signal is controlled by Port 92 or a chipset specific method.

Memory Parity Check

An approach that generates and checks parity on each memory transfer and provides an interrupt if an error is found. This item is to <Disabled> or <Enabled> this function.

Typematic Rate Setting

To enable typematic rate and typematic delay programming. If you disable the typematic rate and typematic delay programming, the system BIOS will use the default value of the keyboard controls these 2 items and the default.

Typematic Rate (Chars/Sec)

Typematic Rate sets the rate at which characters on the screen repeat when a key is pressed and held down. The settings are 6, 8, 10, 12, 15, 20, 24, or 30 characters per second.

Typematic Delay (Msec)

The number selected indicates the time period between two identical characters appearing on screen.

Security Option

The option allows the user to limit access to the System and Setup, or just to Setup.

System	The system will not boot and accesses to Setup will be denied if the correct password is not entered at the prompt.
Setup	The system will boot, but access to Setup will be denied if the correct password is not entered at the prompt.

Note: To disable security, select PASSWORD SETTING at Main Menu and then you will be asked to enter password. Do not type anything and just press <Enter>, it will disable security. Once the security is disabled, the system will boot and you can enter Setup freely.

PCI/VGA Palette Snoop

This option must be set to Enabled if any ISA adapter card installed in the computer requires VGA palette snooping.

Video BIOS Shadow

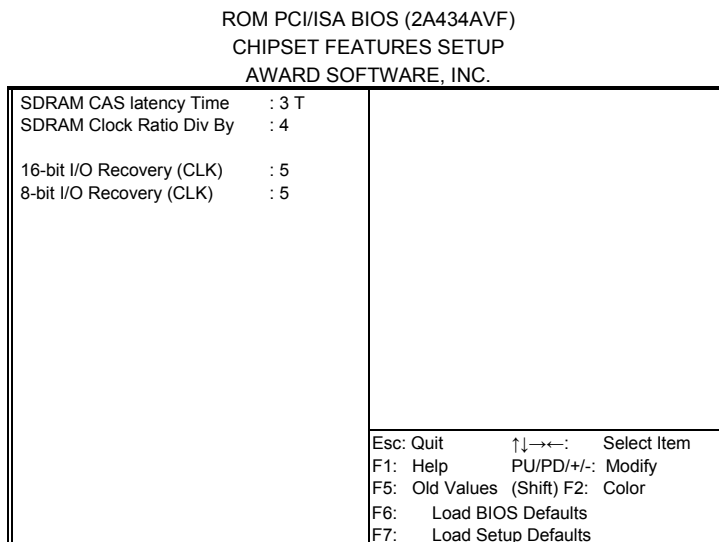
ROM Shadow copies Video BIOS code from slower ROM to faster RAM. Video BIOS can then execute from RAM. This makes your system faster.

Cyrix 6x86/MII CPUID

The option is to determine whether or not to use the function of controlling or accessing the Cyrix 6x86/MII CPUID.

5.4 CHIPSET FEATURES SETUP

This option controls the configuration of the board's chipset. Control keys for this screen are the same as for the previous screen. This selection is automatic.



Chipset Features Setup

SDRAM CAS latency Time

This item is to setup the SDRAM CAS# signal latency time, the smaller value you set it, the higher efficiency you will get.

SDRAM Clock Ratio Div By

This item is to determine the SDRAM Clock Ratio.

16-Bit I/O Cycle Recovery Time

8-Bit I/O Cycle Recovery Time

These options specify the length of the delay (in BUSCLK) inserted between consecutive 8-bit/16-bit I/O operations.

5.7 INTEGRATED PERIPHERALS

This section is designed to configure the peripheral features.

ROM PCI/ISA BIOS (2A434AVF)
 INTEGRATED PERIPHERALS
 AWARD SOFTWARE, INC.

IDE HDD Block Mode	: Enabled		
Primary IDE Channel	: Enabled		
Master Drive PIO Mode	: Auto		
Slave Drive PIO Mode	: Auto		
IDE Primary Master UDMA	: Disabled		
IDE Primary Slave UDMA	: Disabled		
KBC input clock	: 8 MHz		
Onboard Serial Port 1	: 3F8/IRQ4	Multiple Monitor Support	: No Onboard
Onboard Serial Port 2	: 2F8/IRQ3	Video Memory Size	: 2.5M
Onboard IR Controller	: Disabled		
Onboard Parallel Port	378/IRQ7	Esc: Quit	↑↓←→: Select Item
Parallel Port Mode	SPP	F1: Help	PU/PD/+/-: Modify
		F5: Old Values	(Shift) F2: Color
		F6: Load BIOS Defaults	
		F7: Load Setup Defaults	

Integrated Peripherals

IDE HDD Block Mode

This option allows your hard disk controller to use the fast block mode to transfer data to and from your hard disk drive (HDD).

Enabled	IDE controller uses block mode.
Disabled	IDE controller uses standard mode.

IDE PIO

IDE hard drive controllers can support up to two separate hard drives. These drives have a master/slave relationship, which is determined by the cabling configuration used to attach them to the controller. Your system supports one IDE controller – a primary and a secondary – so you have the ability to install up to four separate hard disks.

PIO means Programmed Input/Output. Rather than have the BIOS issue a series of commands to affect a transfer to or from the disk drive, PIO allows the BIOS to tell the controller what it wants and then let the controller and the CPU perform the complete task by themselves. This is simpler and more efficient (and faster). Your system supports five modes, numbered from 0 to 4, which primarily differ in timing. When Auto is selected, the BIOS will select the best available mode.

KBC input clock

This item it to chose the input clock of Keyboard Controller

OnBoard Serial Port 1 & 2

These options are used to select the port address of the on-board serial port A. The options are 3F8H, 2F8H, 3E8H, 2E8H, Auto and Disable. Port 1 is COM A, Port 2 is Com D and so on. Port four can be set to be IrDA (Choose Auto) if the IrDA device has been connected.

OnBoard Parallel Port

This option is used to select the port address of the on-board parallel port. The options are 378H, 278H, 3BCH, and Disabled.

Parallel Port Mode

This option specifies the parallel port Mode. The settings are Printer or Extended (Bi-direction).

Multiple Monitor Support

This is to determine the highest priority that the monitor supports. <PCI First> is the default setting. The other two choices are <No Onboard> and <M/B First>.

5.8 PASSWORD SETTING

This BIOS Setup has an optional password feature. The system can be configured so that all users must enter a password every time the system boots or when BIOS Setup is executed.

5.8.1 Setting Password

Select the appropriate password icon from the Security section of the BIOS Setup main menu. Enter the password and press [Enter]. The screen does not display the characters entered. After the new password is entered, retype the new password as prompted and press [Enter].

If the password confirmation is incorrect, an error message appears. If the new password is entered without error, press [Esc] to return to the BIOS Main Menu. The password is stored in CMOS RAM after BIOS is completed. The next time the system boots, the prompt for the password function is present and is enabled.

Enter new supervisor password:

5.8.2 Password Checking

The password check option is enabled in Advanced Setup by choosing either **Always** (the password prompt appears every time the system is powered on) or **Setup** (the password prompt appears only when BIOS is run). The password is stored in CMOS RAM. User can enter a password by typing with the keyboard. Enter a 1-6 character password. The password does not appear on the screen when typed. Make sure you write it down.

5.9 IDE HDD AUTO DETECTION

This option detects the parameters of an IDE hard disk drive, and automatically enters them into the Standard CMOS Setup screen.

5.10 BIOS EXIT

This section is used to exit the BIOS main menu in two types of situation. After making your changes, you can either save them or exit the BIOS menu and without saving the new values.

5.10.1 Save & Exit Setup

This item set in the <Standard CMOS Setup>, <BIOS Features Setup>, <Chipset Features Setup>, <Power Management Setup>, <Integrated Peripherals> and the new password (if it has been changed) will be stored in the CMOS. The CMOS checksum is calculated and written into the CMOS.

As you select this function, the following message will appear at the center of the screen to assist you in saving data to CMOS and Exit the Setup.

Save current settings and exit (Y/N) ?

5.10.2 Exit Without Saving

When you select this option, the following message will appear at the center of the screen to help to abandon all Data and Exit Setup.

Quit without saving (Y/N) ?

Windows Installation Notice:

1. The proper way to setup the Windows system is to copy all the drivers needed to your hard disk or CD-ROM and to execute them from the related devices.
2. Please refer to BIOS setup section in this manual for booting from CD-ROM
3. If you find any difficulty in the operating systems installation, please contact our technical support for further assistance.

Note: If the content in Setting is inconsistent with CD-ROM. Please refer to the Setting as priority.